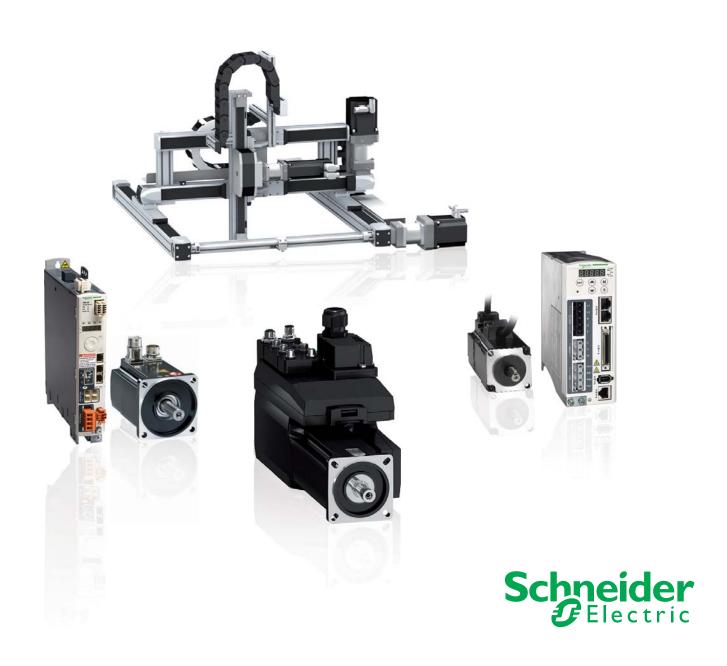
A complete range of motion products for efficient machine automation

Catalog

2013



How to find the "Automation and Control" products

Catalogues
Complete product ranges

Human/Machine interfaces Modicon Quantum automation platform April 2012 nher 2012 Motion control Control and signaling Lexium 23 Plus units Ø 22 nuary 2013 Variable speed drives Δl+ivar 12 Motion centric machine automation with PacDrive 3 Schneider

Selection of the top selling products



General contents

General presentation	·
Selection guide	;
Servo drives and motors	
Integrated drives	
Linear Motion	



- A complete product range
- > solution competency
- > the power of motion
- > connectivity
- > global availability

make Schneider Electric your partner of choice for cost-effective and energy-efficient machine automation

Schneider Electric, you can rely on us!

Maximum productivity for your machines

Complete Motion offer

- > Complete and scalable motion range with outstanding servo control loops for virtually all kinds of machines
- > Wide range of linear motion and robotic products and capacity for customization and 3rd party motors

Simplicity

- > Our motion products are designed for maximum simplicity over the entire machine lifecycle to reduce costs and make your machine processes even more productive
- > Our motion products are easy to integrate into your machine environments through standard software tools, motion libraries and application function blocks

Openness

- Our products support standardized motion interfaces: CANopen, CANmotion, Profibus, DeviceNet, Ethernet IP, EtherCAT, Ethernet Powerlink, Modbus TCP and Pulse Train
- > This allows you to efficiently design machines which can easily be integrated into your customers' automation architectures

Safety

- > Safe Torque Off (STO) embedded in the drives
- Advanced safety functions: Safe Stop (SS1, SS2), Safety Limited Speed (SLS), Safe Operating Stop (SOS) as option available

With superior performance in the market and embedded safety, our wide range of motion products supports standardized motion interfaces to assist integration.

If you need even more performance, our PacDrive offer is your product of choice. With its centralized system architecture, PacDrive is the ideal solution for controlling a broad range of servo-driven production and packaging machines, as well as material handling equipment.



from coordinated ...

... to synchronized motion control

Whatever your performance needs are, our high-performance drives and motors offer a range of choices

If you need coordinated or synchronized motion control, Schneider Electric offers a wide range of servo drives and integrated drives for machine automation. With a power range up to 25 kW there is the right drive for your application.

Lexium 52/62

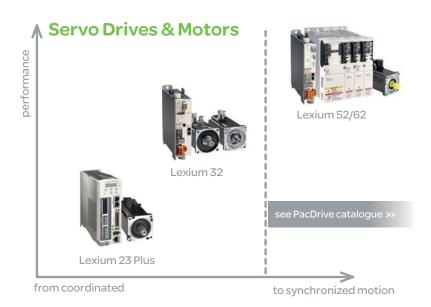
- > High-Performance servo drive
- > Single (LXM52) and multi axis (LXM62)
- > Safety on Sercos
- > 0.4 kW to 25 kW

Lexium 32

- > Flexible servo drive
- > Powerful control loop
- > Embedded safety
- > 0.15 kW to 7 kW

Lexium 23 Plus

- > Optimized servo drive
- > Small form factor
- > 0.1 kW to 7.5 kW



Lexium ILM62

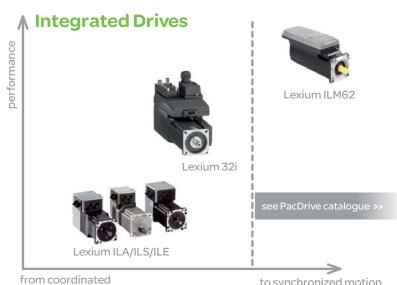
- > Single cable solution
- > Sercos interface
- > Safety on Sercos
- > 0.3 kW to 2 kW

Lexium 32i

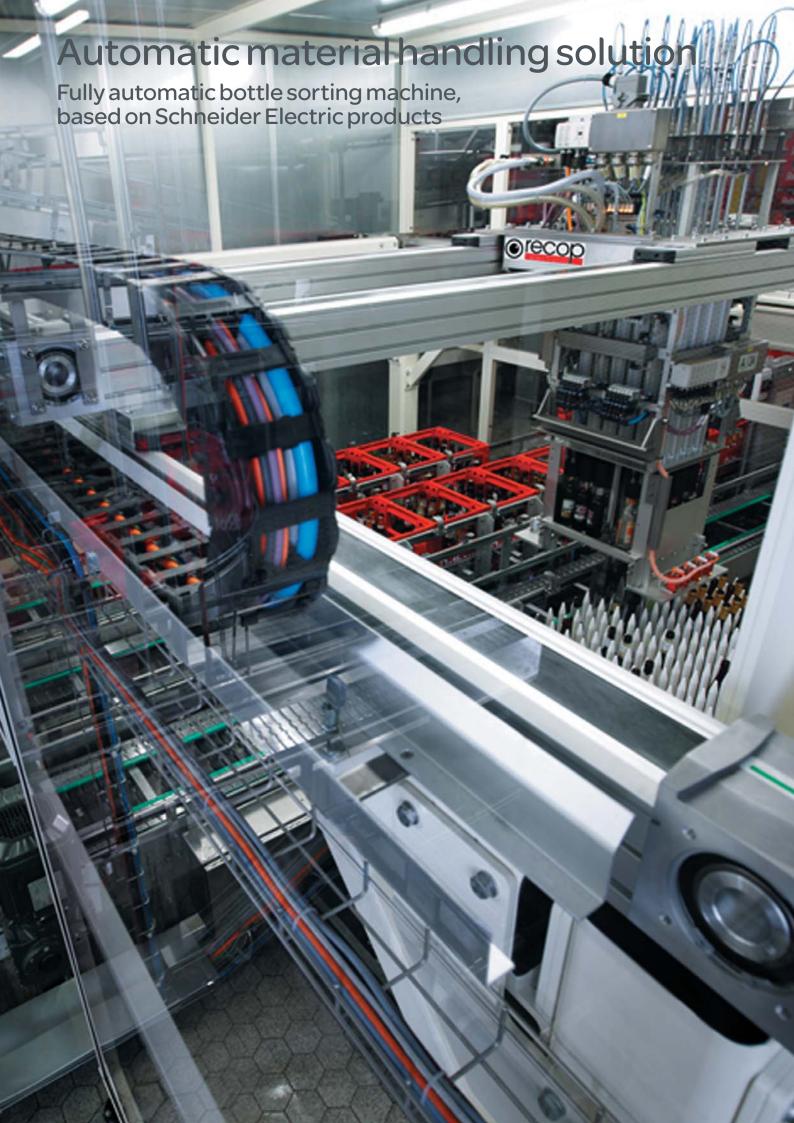
- > Modular servo drive
- > CANmotion interfaces
- > Embedded safety
- > 0.6 kW to 2.2 kW

Lexium ILA/ILS/ILE

- > Extremly compact drive
- > Servo, stepper and brushless
- > Large choice of interfaces
- > 0.1 kW to 0.4 kW



to synchronized motion



Machine **2** truxure



- > Predetermined equipment lists
- > **Tested**: in various possible configurations for proper function relative to performance
- > Validated: functional compatibility of devices
- Documented: a complete system user guide, predefined CAD panel design and wiring diagrams

Reduce your machine's time-to-market with Tested, Validated and Documented Architectures and function blocks

The choice of automation solutions is now, more than ever, a determining factor in supplying machines with shorter lead times that are more efficient, productive and reliable, at a reduced cost.

To meet this demand, Schneider Electric offers MachineStruxure[™] automation solutions, which help machine builders to quickly design machines that are optimized with regard to costs and energy efficiency, whilst maximizing their performance throughout the service life of the machine. MachineStruxure[™] solutions propose Tested, Validated and Documented Architectures with standard or application function block libraries.

Machine solution





Application functions

- Grouping/Ungrouping
- 2 Lateral position control
- 3 Digital tension control
 Analog 1m tension control
- 4 Rotary knives
- Heating temperature control
- 6 Flying shear

Motion products

- Modicon LMC058 controller
- 2 Lexium 32 servo drive
- 3 Lexium BMH and BSH servo motors
- 4 Lexium 32i integrated servo drive
- Lexium MAX R3 multi-axis system

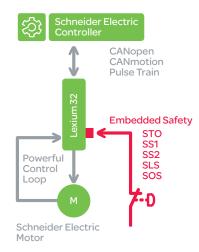


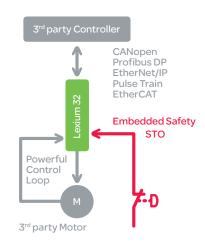
- > Easy to integrate in your architecture
- > Cost-effective solution
- > Superior control loop performance
- > Embedded safety functions

Whatever your architectures is like, our high-performance drives are easy to integrate

Schneider Electric offers a complete range of servo and integrated servo drives that allows you to realise any kind of motion architectures and applications. Regardless whether you work within a Schneider Electric solution or if you integrate the motion devices and functions in your own architecture.

Schneider Electric's offer helps you make the right choice.





Motion control	Coord	inated moveme	ents			Synchroniz	ed movement	s
Drives Interfac	ce CANo	oen Profibus D	P Ethernet I/I	P Modbus TCP	Ethernet Powerlink	Pulse Train	CANmotion	EtherCAT
Lexium 23 Plus	✓					✓	✓	
Lexium 32	✓	✓	✓			✓	✓	✓
Lexium 32i	✓						✓	✓
Lexium ILA, ILE,	ILS 🗸	✓	✓	✓	✓	✓		✓



Embedded safety function

- Simplified machine design and engineering
- > Less wiring
- > Simpler sensor systems
- Shorter downtimes; resume exactly to the stage in progress before an incident. Compliance with international standards
- Machine certification is made a lot easier



eSM optional safety module

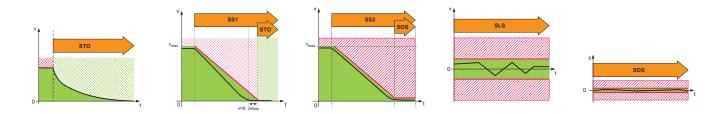
Embedded safety, get rid of the hassle of devising complex, proprietary safety concepts

Safety is a complex and costly issue in the design and operation of a machine. To make things a lot simpler for you, Schneider Electric servo and integrated drives come with "Safe Torque Off" (1) on board in accordance with the IEC/EN 61800-5-2 standard. This function is compliant with and certified according to international standards and provides numerous benefits.

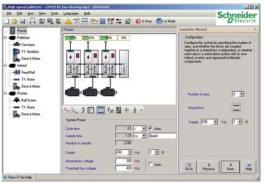
Additional safety

If your machine requires more safety functions than "Safe Torque Off", you can simply install the optional enhanced safety module eSM into the Lexium 32 servo drive. This module offers eSM safety module functions in accordance with the IEC/EN 61800-5-2 standard.

(1) Except Lexium 23 Plus.



Embedded Safety Drives	STO	SS1	SS2	SLS	sos
Lexium 23 Plus					
Lexium 32	✓	✓eSM	✓eSM	✓eSM	✓eSM
Lexium 32i	✓				
Lexium ILA, ILE, ILP	/				



Sizing tool

Easily find the right product for your application

The user-friendly sizing tool helps you to find the right servo drives and motors for your machine. It includes different mechanisms, mechanical transformations and gearboxes.

The complete project can be captured in one file which provides detailed power flow, energy storage analysis and accurate energy consumption.

To determine the size of your drives and motors, please contact our Customer Care Centre.

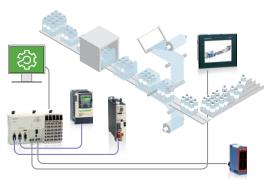


Configuration tool on www.schneider-electric.com

Configure your motion product in just a few clicks

Our graphical configurators simplify the configuration of motion products and their accessories. In just a few clicks, and without any assistance or in-depth knowledge of the range, you are guided to make your choices.

A bill of materials needed for your motion product will be created and can be exported in MS Excel or PDF format to simplify your ordering process.



Packaging solution



Drive configuration with SoMove software

SoMachine simplifies the programming of your machine

The SoMachine™ Software offers 100% flexibility and optimization by allowing you to design, commission and service machines in a single software suite, resulting in a significant competitive advantage.

Decrease total machine cost by using a single environment and reducing design time

- > Install components in one step
- > One software for controllers, HMI and remote devices
- > Access to networked devices in pure transparency
- > Connect your cable only once, and download from our website with a single click
- > Re-use Schneider Electric's expertise and know-how with ready-to-use Application Function Blocks, templates and fully tested, validated and documented automation architectures

SoMachine simplifies the commissioning of your drive

The SoMove software incorporates various functions for the device setup phases, such as configuration preparation, setup and maintenance.

A true offline mode allows:

- > Preparation of configuration files
- > File management and storage (save to hard disk or CD ROM, copy, rename and send by email, etc.)
- > Printing of the settings list
- > Preparation of files for the Multi-Loader and SoMove Mobile tools

The online mode is used to:

- > Configure, adjust, control and monitor
- > Transfer configuration files between SoMove V1.0 and the drive or soft starter

To facilitate setup and maintenance, SoMove

- > Can use a direct USB/RJ45 cable link or Bluetooth® wireless link
- > Is compatible with the Multi-Loader configuration tool and SoMove Mobile

Increase your efficiency and competitiveness with our services and support



Design

Let's find the right solution for you

- Application Design Experts (ADEs), Solution and Architecture Experts (SAEs) are available to assist you. They understand your needs and can propose innovative technical solutions including
 - > Advice
 - > Co-engineering services
 - > Feasibility testing and validation

Our consulting services are there to help

- > We understand your pain points and can propose the solutions to solve them
- > Audits

We execute the solution

- Our solution design and delivery centers (Flex-Centers) are committed to quality results and schedules
 - > Project and program management
 - > Software and hardware engineering
- > Testing, validating and commissioning the solution

Improve your team's competencies

- > Classroom-based training
- > On-site training



Build

We deliver the solution

- > Availability of components
 - > Large worldwide network of distributors
- > Delivery through local partners
- > Collaboration and management of partners
- Schneider Electric as your solution provider
 - > Project management and responsibility
 - > Engineered solutions
 - > Third-party components (suppliers)

We improve services and support on your site

Secondment of qualified personnel to deliver on-site engineering and technical services

We improve your service team's competencies

Service and commissioning training



With MachineStruxure, make your machines stand out right from the start





Provide services and support to you and your customers

- > Maintenance contracts
- > Spare parts
- > Repairs
- > Standard and express deliveries
- > Return of goods
- > Service expertise
 - > Preventive maintenance
 - > Contract extension
- > Customer International Support (CIS) as contact point
 - > Find the closest expert to solve your technical questions

Improve your customer's competencies

- > Classroom-based customer training
- > On-site training
- > Service and commissioning training





Improve your machine range

> Consulting

Improve the machine in the production line

- > Audit
- > Services and Expertise
 - > Contract extension
 - > Upgrading
 - > Migration
- > Training



With MachineStruxure, benefit from worldwide assistance and after-sales support

Drives, motors and linear motion axes

Applications

Servo Drives and Motors

Lexium servo drives are the perfect drives for applications involving high-precision and dynamic positioning

Lexium 23 Plus and BCH motor

Lexium 32 and BMH or BSH motor







Description		The Lexium 23 Plus servo range consists of two book-size servo drive models, Lexium 23A with CANopen interface, Lexium 23D with pulse train interface plus the motor family Lexium BCH from ultra low inertia to high inertia.	The Lexium 32 servo range consists of three high-performance book-size servo drive models, Lexium 32 Compact, Lexium 32 Advanced and Lexium 32 Modular, and two motor families, the versatile medium-inertia Lexium BMH and the dynamic low-inertia Lexium BSH.
Machines		Textile machines, Electronics machines, Packaging machines, Material working machines, Material handling machines, Printing machines	Packaging machines, Material handling machines, Material working machines, Assembling machines
Technical information	Power range	0.1 kW7.5 kW	0.157 kW
	Voltage range	1 or 3-phase 170255 VAC	1-phase 115240 VAC, 3-phase 208480 VAC
	Speed	1,000 rpm to 3,000 rpm depending on the motor	up to 8,000 rpm
	Torque	up to 47.74 Nm	up to 84 Nm
Interfaces		CANopen	CANopen, CANmotion, PROFIBUS DP, DeviceNet, EtherNet/IP, Pulse train, +/- 10V Encoder modules for digital and analog encoders and resolvers
Safety functions		-	Safe Torque Off (STO) on board Enhanced Safety Module: Safe Stop 1 (SS1), Safe Stop 2 (SS2), Safely Limited Speed (SLS), Safe Operation Stop (SOS)
See page		14	15

Integrated Drives		Linear Motion
Lexium Integrated Drives contribute to extremely sp motion solutions	pace-saving decentralised	Lexium Linear Motion products are designed for maximum flexibility, performance and cost-effectiveness. This range offers products for linear movements in the automation industry from single-axis to multi-axis systems
Lexium ILA, ILE and ILS	Lexium 32i	Lexium PAS, CAS, TAS and MAX











150 - 305 W 1248 VDC 1-phase 115240 VAC, 3-phase 400480 VAC 1-phase 115240 VAC, 3-phase 400480 VAC up to 9,000 rpm up to 12 Nm RS485, CANopen, PROFIBUS DP, DeviceNet, EtherNet/IP, EtherCAT, Ethernet POWERLINK, Modbus TCP, Pulse train Safe Torque Off (STO) on board Safe Torque Off (STO) on board Single axes: Stroke up to 5.5 m Load up to 150 kg Speed up to 8 m/s	Lexium ILx Integrated Drives comprise the motor, positioning controller, power electronics, fieldbus and "Safe Torque Off" function in an extremely compact single device. Lexium ILx Integrated Drives are available with multiple motor technologies (servo, brushless DC, stepper). Format adjustment, Printing machines, Material handling machines	The Lexium 32i is an integrated servo drive and comprises motor, positioning controller, power electronics, fieldbus and "Safe Torque Off" function in an extremely compact single device. Packaging machines, Material handling machines, Material working machines, Assembling machines	Lexium Linear Motion is a comprehensive linear motion range comprising Lexium PAS portal axes, Lexium TAS linear tables, Lexium CAS cantilever and telescopic axes and Lexium MAX multi-axis systems. Material handling machines Material working machines On-the-fly working machines Assembling machines
up to 9,000 rpm up to 12 Nm RS485, CANopen, PROFIBUS DP, DeviceNet, EtherNet/IP, EtherCAT, Ethernet POWERLINK, Modbus TCP, Pulse train Safe Torque Off (STO) on board Speed up to 8 m/s		1-phase 115240 VAC, 3-phase	Stroke up to 5.5 m
up to 12 Nm RS485, CANopen, PROFIBUS DP, DeviceNet, EtherNet/IP, EtherCAT, Ethernet POWERLINK, Modbus TCP, Pulse train Safe Torque Off (STO) on board Up to 7.8 Nm CANopen, CANmotion, EtherCAT Multi axes: Stroke up to 5.5 m Load up to 130 kg Speed up to 4 m/s Available as individual components or completely pre-assembled, customized systems with drives and motors		400480 VAC	
RS485, CANopen, PROFIBUS DP, DeviceNet, EtherNet/IP, EtherCAT, Ethernet POWERLINK, Modbus TCP, Pulse train Safe Torque Off (STO) on board CANopen, CANmotion, EtherCAT Multi axes: Stroke up to 5.5 m Load up to 130 kg Speed up to 4 m/s Available as individual components or completely pre-assembled, customized systems with drives and motors	up to 9,000 rpm	up to 3,600 rpm	-
EtherNet/IP, EtherCAT, Ethernet POWERLINK, Modbus TCP, Pulse train Safe Torque Off (STO) on board	up to 12 Nm	up to 7.8 Nm	-
systems with drives and motors	EtherNet/IP, EtherCAT, Ethernet POWERLINK,	CANopen, CANmotion, EtherCAT	Stroke up to 5.5 m Load up to 130 kg Speed up to 4 m/s
26 27 33	Safe Torque Off (STO) on board	Safe Torque Off (STO) on board	or completely pre-assembled, customized
	26	27	33

Servo Drives and Motors Lexium 23 Plus, Lexium BCH



Lexium 23 Plus servo drives



BCH servo motors

Lexium 23 Plus, the compact servo drive combined with the powerful Lexium BCH servo motor, enhances your installation through added efficiency and flexibility

Easy integration

- > The numerous servo drive functions include speed and torque control, autotuning, and positioning
- Open communication concept enables simple integration within a wide range of different control system architectures

Simple commissioning and lower installation costs

- > The Lexium 23 CT PC commissioning software includes an auto-tuning function which enables extremely fast start-up
- > The simplicity of the Lexium 23 Plus servodrive wiring simplifies installation and reduces global installation costs

Compact range

> The compact size of the Lexium 23 Plus makes it ideal for use where space is limited

Flexibility

Lexium 23 Plus servo drives feature standard digital and analog I/O, and one of the following communication interfaces, depending on the model:

- > Interface for CANopen/CANmotion machine bus (LXM23A)
- > Pulse/direction (P/D) interface (LXM23D)

Servo Drives and Motors Lexium 23 Plus, Lexium BMH, BSH







Lexium 32 Advanced for CANopen or CANmotion architectures



Lexium 32 Modular is open to the world of motion with numerous modules



Simplicity throughout the entire lifecycle of your machine

- > Fast engineering with powerful integration and design software (motor sizing, CAD and cabinet drawings, support for PLCopen libraries, commissioning software SoMove) reduces time-to-market
- > Simplified installation with easy access to removable, color-coded connectors, memory cards and multi-loader
- > Memory card and standardized "Faulty Device Replacement" (FDR) function with EtherNet/IP for fast device replacement
- "Safe Torque Off" function on board

Openness and modularity

- > Intelligent, modular product concept responds to most requirements
- > Large selection of fieldbus modules for fast integration into your architecture
- > 3 encoder modules for machine encoder/second motor encoder
- > eSM module for additional safety functions

Power and performance

- > Easy auto-tuning for different levels of expertise
- > Superior motor control
- > Intelligent vibration and jerk suppression for long machine life
- > Two powerful motor ranges: the versatile medium-inertia Lexium BMH and the dynamic low-inertia Lexium BSH



Lexium BMH is extremely versatile



Lexium BSH is highly dynamic

Servo Drives and Motors Lexium 23 Plus

Main functions	Lexium23A-CAN version	Lexium23D-Pulse Train version
Communication	CANopen CANmotion Pulse Train RS232	Pulse Train RS232
Operating modes	Jog mode Profile Position mode Profile Velocity mode Profile Torque mode Homing mode	Electronic gearbox Positioning mode Speed mode Torque mode
Functions	Auto-tuning 2-notch filters Position capture	Auto-tuning 2-notch filters Position capture
24V logic inputs	8 reassignable	8 reassignable
24V logic outputs	5 reassignable	5 reassignable
Analog inputs	2	2
Pulse control input	RS422 500 kHz (standard)/4 MHz (high-speed) 200 kHz open collector	
ESIM PTO output	1 RS422	1 RS422
Encoder	High-speed pulse train	High-speed pulse train
Architecture	Control via: CANopen CANmotion Pulse Train Analog input	Control via: Pulse Train Analog input
Type of servo drive	Lexium 23A	Lexium 23D

Main functions



Application type		From ultra-low inertia to high inertia, suitable for highly dynamic and high-load applications
Flange size		40, 60, 80, 100, 130 and 180 mm
Continuous stall torque		0.32 to 47.74 Nm
Encoder type		20-bit incremental
Degree of protection	Casing	IP65
	Shaft end	IP40 (standard)/IP65 (option)
Type of servo motor		Lexium BCH

Servo Drives and Motors Lexium 23 Plus

Servo drive	Servo motor	Power (w)	Rated torque (Nm)	Peak torque (Nm)	Rated speed (rpm)	Peak speed (rpm)	Inertial w/o brake (kg cm²)	Motor inertia type
Single-phase: 200255	V 50/60 Hz or three-phase: 170	255 V 50/60 Hz						
LXM23•U01M3X	BCH0401O•2•••	100	0.32	0.96	3000	5000	0.037	ultra low
LXM23•U02M3X	BCH0601O•2•••	200	0.64	1.92	3000	5000	0.177	ultra low
LXM23•U04M3X	BCH1301M•2•••	300	2.86	8.59	1000	2000	8.17	medium
LXM23•U04M3X	BCH0602O•2•••	400	1.27	3.82	3000	5000	0.277	ultra low
LXM23⊕U04M3X	BCH0801O•2•••	400	1.27	3.82	3000	5000	0.68	low
LXM23•U04M3X	BCH1301N•2•••	500	2.39	7.16	2000	3000	8.17	medium
LXM23⊕U07M3X	BCH1302M•2•••	600	5.73	17.19	1000	2000	8.41	medium
LXM23•U07M3X	BCH0802O•2•••	750	2.39	7.16	3000	3000	1.13	low
LXM23•U10M3X	BCH1303M•2•••	900	8.59	25.78	1000	2000	11.18	medium
LXM23•U10M3X	BCH1001O●2●●●	1000	3.18	9.54	3000	5000	2.65	low
LXM23•U10M3X	BCH1302N•2•••	1000	4.77	14.32	2000	3000	11.18	medium
LXM23•U15M3X	BCH1303N•2•••	1500	7.16	21.48	2000	3000	11.18	medium
Three-phase: 170255	V 50/60 Hz							
LXM23•U20M3X	BCH1002O•2•••	2000	6.37	19.11	3000	5000	4.45	low
LXM23•U20M3X	BCH1304N•2•••	2000	9.55	26.65	2000	3000	14.59	medium
LXM23•U20M3X	BCH1801N•2•••	2000	9.55	26.65	2000	3000	34.58	high
LXM23•U30M3X	BCH1802N•2•●●	3000	14.32	42.96	2000	3000	54.95	high
LXM23•U30M3X	BCH1802M•2•••	3000	19.1	57.29	1500	3000	54.95	high
LXM23•U45M3X	BCH1803N•2•●●	3500	16.71	50.31	2000	3000	54.8	high
LXM23•U45M3X	BCH1803M•2•••	4500	28.65	71.62	1500	3000	77.75	high
LXM23•U55M3X	BCH1804M•2•●●	5500	35.01	87.53	1500	3000	99.78	high
LXM23•U75M3X	BCH1805M•2•••	7500	47.74	119.36	1500	3000	142.7	high

Servo Drives and Motors Lexium 32

Main functions		Lexium 32 Compact	Lexium 32 Advanced	Lexium 32 Modular
Communication	Integrated	Modbus serial link Pulse train	Modbus serial link CANopen, CANmotion machine bus	Modbus serial link Pulse train
	As an option	-	-	CANopen, CANmotion machine bus, DeviceNet, EtherNet/IP, PROFIBUS DP, EtherCAT, I/O module
	Operating modes	Manual mode (JOG), Electronic gearbox, Speed control, Current control	Homing, Manual mode (JOG), Speed control, Current control, Position control	Homing, Manual mode (JOG), Motion sequence, Electronic gearbox, Speed control, Current control, Position control
	Functions	Auto-tuning, monitoring, stopping	, conversion	
		-	Stop window, Rapid entry of position values	Stop window, Rapid entry of position values, Rotary axes, Position register
24 V == logic inputs		6, reassignable	3, reassignable	4, reassignable
24 V == capture inputs (1) (2)		-	1	2
24 V == logic outputs (1)		5, reassignable	2, reassignable	3, reassignable
Analog inputs		2	-	
Pulse control input		1, configurable as: RS 422 link 5 V or 24 V push-pull 5 V or 24 V open collector		
ESIM PTO output		RS 422 link		
Safety functions	Integrated	"Safe Torque Off" STO		
	As an option	-		Safe Stop 1 (SS1) and Safe Stop 2 (SS2) Safe Operating Stop (SOS) Safe Limited Speed (SLS)
Sensor	Integrated	SinCos Hiperface® sensor		
	As an option	-		Resolver encoder, Analog encoder, Digital encoder
Architecture		Control via: Logic or analog I/O	Control via: Motion controller via CANopen and CANmotion machine bus	Control via: Schneider Electric or third-party PLCs via communication buses and networks
Type of servo drive		LXM32C	LXM32A	LXM32M

Main functions



Type of servo motor		ВМН	BSH
	Shaft end	IP 50 or IP 65 (IP 67 conformity kit as an option)	
Degree of protection	Casing	IP 65 (IP 67 conformity kit as an option)	
Encoder type		Single turn SinCos: 32,768 points/turn and 131,072 points/turn Multiturn SinCos: 32,768 points/turn x 4,096 turns and 131,072 points/turn x 4,096 turns	Single turn SinCos: 131,072 points/turn Multiturn SinCos: 131,072 points/turn x 4,096 tu
Continuous stall torque		1.2 to 84 Nm	0.5 to 33.4 Nm
Flange size		70, 100, 140 and 190 mm	55, 70, 100 and 140 mm
Application type		High load, With robust adjustment of the movement	High dynamic range, Power density

Servo Drives and Motors Modules for Lexium 32M and setup software

Communication modules



Second encoder modules		
	Machine	Motor



VW3A3601

VW3M3302

Lexium 32M has an input for an additional encoder to connect third-party motors (motor encoder) or to improve positioning accuracy (machine encoder)

Module for digital encoder (A/B/I, BiSS, EndDat 2.2, VW3M3402 Yes SSI) Module for encoder (A Ver / Hell 4 Ver / Hings / VW3M3402 Yes / Hings / Ver / Hings	
Module for engles encoder (4 \/pp /Liner \/\N2M2402	
Module for analog encoder (1 Vpp/Hall, 1 Vpp, Hiper- VW3M3403 Yes (Hiperface only) Yes	
face)	

Safety module



The eSM module allows Lexium 32M servo drives to access additionnal IEC/EN 61800-5-2 safety functions: SS1, SS2, SLS, SOS

Reference The eSM safety module VW3M3501

EtherCAT module with 2 RJ45 connectors

I/O module with 4DI, 2DO, 2AI, 2AO



SoMove setup software

The SoMove setup software is used to configure, adjust, debug and maintain the Lexium 32 servo drive, just like other Schneider Electric variable speed drives and starters.

It communicates via a Bluetooth® wireless link with the servo drive, which is equipped with the

Modbus- Bluetooth® adaptor (VW3A8 114). SoMove Mobile application for mobile phone

The SoMove Mobile software converts any compatible mobile phone into a remote graphic display terminal, offering an identical Human-Machine Interface.

Particularly suitable for on-site or remote maintenance operations, the SoMove Mobile software can be used to print out and save configurations, import them from a PC and export them to a PC, or to a servo drive equipped with the Modbus adaptor via the Bluetooth® wireless link.

Servo Drives and Motors Lexium 32

Lexium 32 servo drive/BMH or BSH servo motor combinations











Servo motors				Lexium 32C, 32A and 32M servo drives					
				100120 V single-phase	e supply voltage with inte	grated EMC filter			
ВМН		BSH		LXM32•U90M2					
(IP50, IP65 or IP6	(IP50, IP65 or IP67) (IP50, IP65 or IP67)		Continuous output curre	ent: 3 A rms					
				Nominal operating point (1)			Stall torques		
Type of servo motor	Rotor inertia	Type of servo motor	Rotor inertia	Nominal torque	Nominal speed	Nominal power	M ₀ /M _{max} (2)		
	kgcm ²		kgcm ²	Nm	rpm	W	Nm/Nm		
		BSH0551T	0.06	0.49	3000	150	0.5/1.5		
		BSH0552T	0.10	0.77	3000	250	0.8/1.9		
		BSH0553T	0.13						
BMH0701T	0.59								
		BSH0701T	0.25						
		BSH0702T	0.41						
BMH0702T	1.13								
BMH0703T	1.67								
		BSH1001T	1.40						
BMH1001T	3.2								
BMH1002T	6.3								

⁽¹⁾ These values are given for a 240 V single-phase supply voltage. (2) $M_{_{0}}$: Continuous stall torque, $M_{_{\max}}$: Peak stall torque.













LXM32•U18M	2			LXM32•D30M2					
Continuous o	utput current: 6 A rm	าร		Continuous output current: 10 A rms					
Nominal opera	ating point (1)		Stall torques	Nominal oper	Stall torques				
Nominal torque	Nominal speed	Nominal power	M ₀ /M _{max} (2)	Nominal torque	Nominal speed	Nominal power	M ₀ / M _{max} (2)		
Nm	rpm	W	Nm/Nm	Nm	rpm	W	Nm/Nm		
1.14	3000	350	1.2/3.3						
1.35	2500	350	1.4/4.2						
1.36	2500	350	1.4/3.5						
				2.07	2500	550	2.2/6.1		
				2.3	2500	600	2.5/6.4		
				3.1	2000	650	3.4/8.7		
				2.75	2500	700	3.3/6.3		
				3.3	2000	700	3.4/8.9		
				3.5	2000	750	6/10.3		

Servo Drives and Motors Lexium 32

Servo motors				Lexium 32C, 32A and 32M servo drives						
				200240 V single	-phase supply voltage	with integrated EMC filt	er			
ВМН		BSH		LXM32•U45M2						
(IP50, IP65 or IF	P65 or IP67) (IP 50, IP65 or IP67) Continuous output current: 1.5 A rms									
				Nominal operating point (1)						
Type of servo motor	Rotor inertia	Type of servo motor	Rotor inertia	Nominal torque	Nominal speed	Nominal power	M ₀ /M _{max} (2)			
	kgcm ²		kgcm ²	Nm	rpm	W	Nm/Nm			
		BSH0551T	0.06	0.45	6000	300	0.5/1.4			
		BSH0552T	0.10							
		BSH0553T	0.13							
		BSH0701T	0.25							
BMH0701T	0.59									
		BSH0702T	0.41							
		BSH0703T	0.58							
BMH0702T	1.13									
		BSH1001T	1.40							
BMH0703T	1.67									
BMH1001T	3.2									
		BSH1002T	2.31							
BMH1002T	6.3									
BMH1003T	9.4									
BMH1401P	16.5									

⁽¹⁾ These values are given for a 240 V single-phase supply voltage. (2) $M_{\rm o}$: Continuous stall torque, $M_{\rm max}$: Peak stall torque.

LXM32•U9	0 M2			LXM32•D1	8M2			LXM32•D	30M2		
Continuou	Continuous output current: 3 A rms			Continuous output current: 6 A rms			Continuous output current: 10 A rms			ms	
Nominal op	perating point	(1)	Stall torques	Nominal op	Nominal operating point (1) Stall torques Nominal operating point (1)			nt (1)	Stall torques		
Nominal torque	Nominal speed	Nominal power	M ₀ /M _{max} (2)	Nominal torque	Nominal speed	Nominal power	$M_0/M_{max}(2)$	Nominal torque	Nominal speed	Nominal power	$M_0/M_{max}(2)$
Nm	rpm	W	Nm/Nm	Nm	rpm	W	Nm/Nm	Nm	rpm	W	Nm/Nm
0.74	6000	450	0.8/2.5								
0.84	6000	550	1.2/3								
0.94	5000	500	1.3/3.5								
1.1	4000	450	1.4/4								
				1.8	5000	950	2.2/7.2				
				2.1	4000	900	2.6/7.4				
				2.1	4000	900	2.5/7.4				
				2.2	4000	900	2.7/7.5				
				2.9	3000	900	3.4/10.2				
				2.8	3000	900	3.4/10.2				
								3.7	4000	1500	5.8/16.4
								4.6	3000	1450	6/18.4
								5.6	2500	1450	8.2/22.8
								6.9	2000	1450	10.3/30.8

Servo Drives and Motors Lexium 32

Lexium 32 servo drive/BMH or BSH servo motor combinations











Servo motors				Lexium 32C, 32A and 32M servo drives 208480 V three-phase supply voltage with integrated EMC filter								
BMH (IP50, IP65 or IP	67)	BSH (IP50, IP 65 or	ID67\	LXM32•U	60N4 us output c	urrant: 1 5 A	rme	LXM32•D	12N4 us output c	urront: 2 A r	me	
(150, 1600 01 16	07)	(150, 1505 01	1607)		perating po				perating po			
Type of	Rotor	Type of	Rotor	Nominal	Nominal	Nominal	$M_0/M_{max}(2)$	Nominal	Nominal	Nominal	$M_0/M_{max}(2)$	
servo motor	inertia	servo motor	inertia	torque	speed	power	o max ·	torque	speed	power	U IIIax · ·	
	kgcm ²		kgcm ²	Nm	rpm	W	Nm/Nm	Nm	rpm	W	Nm/Nm	
		BSH0551P	0.06	0.48	6000	300	0.5/1.5					
		BSH0552P	0.10	0.65	6000	400	0.8/2.5					
		BSH0553P	0.13	0.65	6000	400	1.05/3.5					
BMH0701P	0.59			1.1	3000	350	1.2/4.2					
BMH0701P	0.59							1.3	5000	700	1.4/4.2	
		BSH0701P	0.25					1.32	5000	700	1.4/3.5	
		BSH0702P	0.41					1.64	5000	850	2.2/7.6	
BMH1001P	3.2							1.9	4000	800	3.3/10.8	
BMH0702P	1.13							2.2	3000	700	2.5/7.4	
BMH0703P	1.67											
		BSH0703P	0.58									
		BSH1001P	1.40									
BMH1001P	3.2											
BMH1002P	6.3											
		BSH1002P	2.31									
BMH1003P	9.4											
		BSH1003P	3.2									
BMH1401P	16.5											
		BSH1004P	4.2									
		BSH1401P	7.4									
BMH1402P	32.0											
		BSH1402T	12.7									
		BSH 1403T	17.9									
BMH1403P	47.5											
		BSH1404P	23.7									
BMH1901P	67.7											
BMH1902P	130											
BMH1903P	194											

⁽¹⁾ These values are given for a 240 V single-phase supply voltage. (2) $M_{\rm o}$: Continuous stall torque, $M_{\rm max}$: Peak stall torque.



LXM32•D1	I 8N4 is output curi	rent: 6 A rms		LXM32•D3	60N4 s output curr	ent: 10 A rms	:	LXM 32•D72N4 Continuous output current: 24 A rms				
Nominal o	perating poir	nt (1)	Stall torques	Nominal o	perating poin	t (1)	Stall torques	torques Nominal operating p		Nominal operating point (1) Sta		Stall torques
Nominal torque	Nominal speed	Nominal power	M ₀ /M _{max} (2)	Nominal torque	Nominal speed	Nominal power	M ₀ / M _{max} (2)	Nominal torque	Nominal speed	Nominal power	$M_0/M_{\text{max}}(2)$	
Nm	rpm	W	Nm/Nm	Nm	rpm	W	Nm/Nm	Nm	rpm	W	Nm/Nm	
2.4	5000	1300	3.4/10.2									
2.44	5000	1300	3.1/11.3									
2.7	4000	1100	3.3/9.6									
3.1	4000	1300	3.4/10.2									
3.9	4000	1600	6.2/18.4									
4	4000	1700	5.8/18.3									
				6.2	4000	2600	8.4/25.1					
				6.3	3000	2000	8/28.3					
				7.6	3000	2400	10.3/30.8					
				8.3	2500	2100	10/37.9					
				9.5	2500	2500	11.1/27					
								12.1	3000	3800	16.8/50.3	
								12.3	3000	3900	19.5/59.3	
								12.9	3000	4100	27.8/90.2	
								14.2	3000	4500	24/71.8	
								19	2500	5000	33.4/103.6	
								18.4	2 500	4 800	30/77.7	
								22.3	2 500	5 900	37.4/101	
								36	1 500	5 700	43.2/123	

Integrated Drives Lexium ILA, ILE, ILS



Lexium ILE with brushless DC motor



Lexium ILA with AC synchronous servo motor



Lexium ILS with 3-phase stepper motor

The Lexium IL● comprises the motor, positioning controller, power electronics, fieldbus and "Safe Torque Off" function in an extremely compact single device

Compact and cost-effective

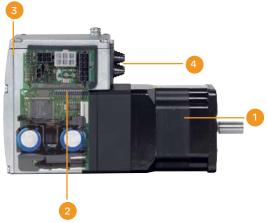
- > An unprecedented level of integration for new dimensions in machine planning, design and installation
- Reduced cabinet size, less air conditioning in cabinet, less wiring and smaller machine footprint, resulting in reduced complexity and cost
- > Same level of performance as any integrated drive, even with dimensions as small as 57 x 100 x 92 mm (W x L x H, Lexium ILS)

Flexible and modular machine concepts

- > Three motor technologies servo, brushless DC, stepper allow you to combine the individual benefits of each technology: dynamics, flexibility, precision
- > 8 fieldbuses for seamless integration into industrial automation environments (RS 485, Profibus DP, CANopen, DeviceNet, Ethernet Powerlink, EtherCAT, Modbus TCP, EtherNet/IP)
- > Versatile connection via PCB connectors or industrial connectors



- > Easy and reduced wiring
- > Integrated EMC filter
- > Fast and simple commissioning with user-friendly commissioning software
- > PLCopen application function blocks included
- > "Safe Torque Off" function on board



- Three motor technologies
- Integrated electronics
- 3 Integrated fieldbus
- 4 Flexible connection technologies

Integrated Drives Lexium 32i

powerful Lexium BMI motor in one single unit. Its modular concept allows you to find the most suitable drive for your motion application



Lexium 32i

- I/O and fieldbus connector module
- Power supply connector module
- **Drive control unit**
- Motor with power stage

Flexibility

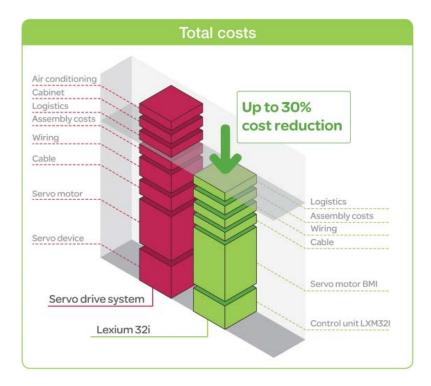
- > Create your own drive to suit your needs by using a combination of the four components to build a product that meets your specific application requirements
- > I/O and flieldbus modules are available with industrial connectors or with a terminal connector module which can be mounted on the top or on the rear of the product

Simplicity

- > Thanks to Schneider Electric's on-line configurator, it is easy to select the four catalogued components which will make your Lexium 32i dedicated to your
- > The four components are easy to assemble, simply click on each component and attach
- > Settings can be stored on the optional Multi Loader or memory card. Simply insert the card to reload them in the device

Cost efficiency

- > Reduce cabinet space by up to 60%: unlike traditional servo drives that are installed in a cabinet, the Lexium 32i is installed directly on the machine to help you improve cost and energy efficiency
- > Reduce total cost of ownership by up to 30% due to less cabinet cooling, no need for motor cables or cabinet space for the drive
- > Reduce assembly time with simplified wiring and easy cabling



Integrated Drives Lexium IL●

Integrated Drives		Lexium ILA	Lexium ILE	Lexium ILS			
Type of process		Dynamic process and accurate positioning	Automatic format adjustment	Short distance movements with accurate positioning			
Type of technology		Integrated drive with servo motor	Integrated drive with DC brushless motor	Integrated drive with three-phase stepper motor			
Main characteristics		Highly dynamic Compact Integrated holding brake as an option	High holding torque without power Integrated gearbox as an option	High torque at low speed			
Dynamic		***	**	***			
Precision and stability		***	**	***			
Energy saving		****	***	**			
Motor inertia		Medium					
Control interface	Control signals	Input/output	Pulse/direction Input/output				
	Buses and networks	CANopen, PROFIBUS DP, RS 485 serial link, DeviceNet, EtherCAT, Modbus TCP, Ethernet Powerlink, EtherNet/IP					
	Motion bus	-					
Drive/motor	Nominal power	150350 W	100350 W	100350 W			
combinations	Nominal speed	5009000 rpm	15007000 rpm	01000 rpm			
	Nominal torque	0.260.78 Nm	0.180.5 Nm	0.456 Nm			
Drive characteristics	Safety function	"Safe Torque Off"					
Power supply		2448 VDC max. 10 A					
Motor characteristics	Type of sensor (resolution)	Single-turn SinCos encoder (16,384 increments/turn) Multiturn SinCos encoder (16,384 increments/turn × 4,096 turns)	Absolute value encoder (121,380 increments/turn)	Index pulse monitoring			
	Motor flange size	57	66	57, 85			
Accessories		Cable, Connector kits, Installation	n sets, Commissioning tools, Pla	anetary gearboxes			

ILA

ILE

ILS

References

Integrated Drives Lexium ILA/ILE/ILS

Lexium ILA with servo motor	Nominal torque	Maximum torque	Nominal speed	Maximum speed	Nominal
	(Nm)	(Nm)	(rpm)	(rpm)	power (W)



ILA1 for CANopen, PROFIBUS DP, RS485									
ILA1•571P	0.26	0.6	5500	7500	150				
ILA1•571T	0.26	0.43	7500	11500	200				
ILA1•572P	0.45	0.72	4300	6200	200				
ILA1●572T	0.41	0.61	5000	7500	215				
ILA2 for DeviceNet, EtherCAT, EtherNet/IP, Modbus TCP, Ethernet Powerlink									
ILA2•571P	0.44	0.62	5100	7000	235				
ILA2•571T	0.31	0.45	7000	9000	255				
ILA2•572P	0.78	1.62	3400	4300	275				
ILA2●572T	0.57	0.85	5100	6800	305				

Lexium ILE with integral spur gearbox.

Ratios:18:1, 38:1, 54:1, 115:1

Lexium ILE with integral worm gearbox with hollow shaft. Ratios: 24:1, 54:1, 92:1, 115:1

ILE1•661

Lexium ILE with brushless DC motor	Nominal torque (Nm)	Detent torque (Nm)	Nominal speed (rpm)	Maximum speed (rpm)
	-			



Lexium ILS with three-phase stepper	Maximum torque	Holding torque	Speed	
ILE2•662	0.5	0.106	5000	7000
ILE2●661 worm gearing	up to 10.6	up to 16.7	44	44
ILE2●661 spur gearing	up to 12	up to 9.19	44	44
ILE2•661	0.26	0.08	6000	7000





ILS1 for CANopen, PROFIBUS DP, RS485, Pulse-Direction, Motion Sequence Mode						
0.45	0.51	1000				
0.9	1.02	600				
1.5	1.7	450				
2.0	2.0	450				
4.0	4.0	200				
6.0	6.0	120				
4.5	4.5	300				
s TCP, Ethernet Power	link					
0.45	0.51	1100				
0.9	1.02	900				
1.5	1.7	600				
2.0	2.0	600				
4.0	4.0	380				
6.0	6.0	200				
4.5	4.5	300				
	0.45 0.9 1.5 2.0 4.0 6.0 4.5 TCP, Ethernet Power 0.45 0.9 1.5 2.0 4.0 6.0	0.45 0.51 0.9 1.02 1.5 1.7 2.0 2.0 4.0 6.0 4.5 4.5 5 TCP, Ethernet Powerlink 0.45 0.51 0.9 1.02 1.5 1.7 2.0 2.0 4.0 6.0 6.0 6.0				

Integrated servo drive Lexium 32i

Main functions

Drive control unit



Communication	Interfaces	Modbus serial link	
		CANopen, CANmotion, EtherCAT	
	Operating modes	Homing	
		Manual mode (JOG)	
		Speed control	
		Current control	
		Position control	
	Functions	Auto-tuning, monitoring, stopping, conversion	
		Stop window	
		Rapid entry of position values	
24 V logic inputs		4	
24 V logic outputs		2	
Safety function		"Safe Torque Off" STO	
Architecture		Control via:	Control via:
		Motion controller via CANopen	EtherCAT
		CANmotion machine bus	
Type of servo drive		LXM32ICAN	LXM32IECT

Drive control unit LXM32I- CAN LXM32IECT





Description	Connector for bus	Number of I/O	STO function		
Industrial connector module for I/O and fieldbus	2 M12 connectors	4 logic inputs with M8	Yes	VW3M9101	VW3M9106
Positive logic inputs (Source)		connectors	-	VW3M9102	VW3M9107
		2 logic inputs with M8	Yes	VW3M9103	VW3M9108
		connector	-	VW3M9104	VW3M9109
Industrial connector module for I/O and fieldbus	2 M12 connectors	4 logic inputs with M8	Yes	VW3M9201	VW3M9206
Negative logic inputs (Sink)		connectors	-	VW3M9202	VW3M9207
		2 logic inputs with M8	Yes	VW3M9203	VW3M9208
		connectors	-	VW3M9204	VW3M9209
Terminal connector module for I/O and fieldbus	_	4 logic inputs	Yes	VW3M9105	VW3M9110
Top part with eight drill holes for cable gland (3): 6 x M12 and 2 x		2 logic outputs			
M16					

Description	Reference
-------------	-----------



Single-phase power supply module for Lexium 32i	VW3M9001
Three-phase power supply module for Lexium 32i	VW3M9002

Integrated servo drive Lexium 32i, Lexium BMI servo motor

Main functions

Servo motor



Application type		High load, With robust adjustment of the movement
Flange size		70, 100
Nominal torque		2.2 to 5.6 Nm
Encoder type		Single-turn SinCos: 32,768 points/turn and 131,072 points/turn
		Multiturn SinCos: 32,768 points/turn x 4,096 turns and 131,072 points/turn x 4,096 turns
Degree of protection	Casing	IP65
Shaft end		IP54 or IP 65
Type of servo motor		BMI

Lexium BMI servo motor					
Power supply		115 V single-phase su	pply		
Type of servo motor	Rotor inertia kgcm²	Nominal operating point (1)			Stall torques M ₀ /M _{max} (2)
	without brake	Nominal torque (Nm)	Nominal speed (rpm)	Nominal power (kW)	Nm/Nm
BMI702T	1.13	2.2	1700	0.4	2.3/6.6
BMI703T	1.67	2.9	1400	0.4	3/8.6
BMI1002T	6.28	5.4	1400	0.75	5.4/14.5

Power supply		230 V single-phase su	upply		
Type of servo motor	Rotor inertia kgcm²	Nominal operating po	int (1)		Stall torques M ₀ /M _{max} (2)
	without brake	Nominal torque (Nm)	Nominal speed (rpm)	Nominal power (kW)	Nm/Nm
BMI702T	1.13	1.7	4000	0.7	2.3/6.6
BMI703T	1.67	2.2	3200	0.7	3/8.6
BMI1002T	6.28	4.4	3000	1.3	5.4/14.5

Power supply		208 V three-phase su	pply		
Type of servo motor	Rotor inertia kgcm²	Nominal operating point (1)			Stall torques M ₀ /M _{max} (2)
	without brake	Nominal torque (Nm)	Nominal speed (rpm)	Nominal power (kW)	Nm/Nm
BMI702P	1.13	2.4	1800	0.4	2.5/6.8
BMI703P	1.67	2.9	1600	0.45	3/8.6
BMI1002P	6.28	5.4	1900	1	5.4/14
BMI1003P	9.37	7.2	1500	1	7.2/19.2

Power supply		400 V three-phase su	pply		
Type of servo motor	Rotor inertia kgcm²	Nominal operating point (1)			Stall torques M ₀ /M _{max} (2)
	without brake	Nominal torque (Nm)	Nominal speed (rpm)	Nominal power (kW)	Nm/Nm
BMI07021•13	1.13	2.2	3600	0.8	2.5/6.8
BMI07031•67	1.67	2.7	3300	0.9	3/8.6
BMI10026•28	6.28	5.1	3800	1.9	5.4/14
BMI10039•37	9.37	6.8	3000	2	7.2/19.2

Power supply		480 V three-phase supply			
Type of servo motor	Rotor inertia kgcm²	Nominal operating point (1)			Stall torques M ₀ /M _{max} (2)
	without brake	Nominal torque (Nm)	Nominal speed (rpm)	Nominal power (kW)	Nm/Nm
BMI07021•13	1.13	2	4400	0.9	2.5/6.8
BMI07031•67	1.67	2.3	3900	0.9	3/8.6
BMI10026•28	6.28	4.1	4700	1.9	5.4/14
BMI10039•37	9.37	5.6	3700	2.1	7.2/19.2

⁽¹⁾ These values are given for a 240 V single-phase supply voltage.

⁽²⁾ M_o : Continuous stall torque, M_{max} : Peak stall torque

Automatic Store and Pick System

Fully automatic dispensary system for pharmacies, based on Schneider Electric products



Linear Motion Lexium PAS, TAS, CAS, MAX



Lexium MAX
Multi-axis systems for 2 or
3-dimensional positioning



Lexium CAS Standardised cantilever and telescopic axes



Lexium PAS Portal axes with fixed-axis body and moving carriage

Lexium Linear Motion is a comprehensive linear motion range comprising Lexium PAS portal axes, Lexium TAS linear tables, Lexium CAS cantilever and telescopic axes and Lexium MAX multi-axis systems

Solutions for numerous linear motion tasks

- > For axis systems below, above and next to the working area, with any combination of arrangements
- > Up to three dimensions with stroke lengths of up to 5500 mm
- > Any combination of axis types

Modular kit system for consistent, easy mounting and maintenance

- > Axes with identical adaptation and motor interfaces
- > < 5 minutes for motor replacement due to flexible adaptation
- > Large selection of versions, e.g. for special ambient conditions (corrosion-resistant)
- > Completely pre-assembled with energy supply chain
- Common spare parts
- > Optimized parts logistics

Customized and complete solutions

- Single-axis and multi-axis systems adapted to individual requirements in terms of length and stroke, precise to within a millimeter
- > Available with mounted motors and/or gearboxes
- > Complete systems available including controllers, drives and motors

Linear Motion Linear axes

Product Lexium PAS B Lexium PAS S





Axis type		Portal axes				
Movement Number of directions		1				
	Movement type	Typically horizontal				
	Position of the load	On carriage				
Drive		Toothed belt	Ballscrew			
Type of guide		Ball or roller	Ball			
Main characteristics		High dynamic response, Long stroke length, High positioning speed	High precision movement (positioning, repeatability, guiding), High feed forces, High rigidity			
Dynamic response		****	***			
Precision		***	****			
Maximum payload		100 kg	100 kg			
Maximum driving force		2600 N	4520 N			
Maximum speed of movement	of the load	8 m/s	1.25 m/s			
Maximum working stroke		5500 mm	3000 mm			
Repeatability		± 0.05 mm	± 0.02 mm			
Options		Choice of guide type: Ball (for applications requiring high forces and torques) or roller (simple, cost-effective solution), Wide range of sensors, Choice of carriage type for adapting to the load, Option to add carriages, Protective metal strip	Choice of pitch, Protective metal strip, Wide range of sensors, Choice of carriage type for adapting to the load, Option to add carriages, Option to add ballscrew supports for longer axes			
Reference		PAS4•B	PAS4•S			

Lexium TAS	Lexium CAS 4	Lexium CAS 3	Lexium CAS 2
Linear tables	Cantilever axes with mobile structure on profile	Cantilever axes with mobile structure on parallel rods	Telescopic axes
1			
Typically horizontal	Typically vertical		Typically horizontal
On carriage	On the side of the profile or on the 2 end blocks	On the 2 end blocks	On carriage
Ballscrew	Toothed belt	Toothed belt or rack	Toothed belt
Double, ball	Ball or roller	Ball	Ball or roller
High precision movement (positioning, repeatability, guiding), High feed forces, High rigidity, Feed movement without mechanical backlash	Long stroke length, High feed forces, Option to mount the load on the side of the profile or on the end blocks, High rigidity	Compact, Mobile structure with light travel weight	Long stroke length from a compact unit, High rigidity, High dynamic response
**	***	***	***
****	***	***	**
150 kg	50 kg	18 kg	35 kg
2580 N	2150 N	705 N	1500 N
1 m/s	3 m/s	3 m/s	3 m/s
1500 mm	1200 mm	500 mm	2400 mm
± 0.02 mm	± 0.05 mm	± 0.05 mm	± 0.1 mm
Choice of pitch, Several different motor mounting options	Choice of guide type: Ball (for applications requiring high forces and torques) or roller (simple, cost-effective solution), Protective metal strip, Anti-corrosion version, Wide range of sensors		Choice of guide type: Ball (for applications requiring high forces and torques) or roller (simple, cost-effective solution), Choice of carriage type for adapting to the load
TAS4	CAS4	CAS3	CAS2

Linear Motion Multi-axis systems

Product	Lexium MAXH	Lexium MAXS





Axis type		Double portal axes				
"		·	·			
Movement	Number of directions	1				
	Movement type	Combination of two parallel axes				
	Position of the load	On two parallel carriages	On two parallel carriages			
Multi-axis system type		PAS 4•B axes + PAS 4•H support axis (driven by the load)	PAS 4●B + PAS 4●B axes (shaft-driven)			
Drive		Toothed belt on one axis	Toothed belt on both axes			
Type of guide		Ball or roller	Ball or roller			
Main characteristics		☐ Long stroke length, High dynamic response, High precision movement (positioning, guiding)	□ Long stroke length, High precision movement (positioning, guiding), High feed forces			
Maximum payload		250 kg	300 kg			
Maximum working stroke	On the X-axis	5500 mm				
	On the Y-axis	-	-			
	On the Z-axis	-	-			
Options		cost-effective solution), Protective metal strip, An	☐ Choice of guide type: Ball (for applications requiring high forces and torques) or roller (simple, cost-effective solution), Protective metal strip, Anti-corrosion version, Anti-static belt, Wide range of sensors, Several different motor mounting options, Variable distance between the two axes			
Reference		MAXH	MAXS			

Lexium MAXP	Lexium MAXR2	Lexium MAXR3
Linear positioners	Portal robots	
2		3
Horizontal and vertical: Combination of one X-axis and one Z-axis	Horizontal: Combination of two perpendicular axes X and Y	Horizontal and vertical: Combination of two perpendicular axes X and Y and one Z-axis
On the side or on the end blocks of the Z-axis profile	On the Y-axis carriage	On the side or on the end blocks of the Z-axis profile
MAXS+CAS4axes MAXS+CAS3axes	MAXS+MAXH axes MAXS+PAS4•B axes	MAXS+MAXH+CAS4axes MAXS+MAXH+CAS3axes
Toothed belt on each axis		
Ball or roller		
□ Dynamic load positioning	□ Long stroke length on both axes	□ Long stroke length on three axes
50 kg	130 kg	50 kg
5500 mm		
-	1500 mm	1500 mm
1200 mm	-	1200 mm

□ Choice of guide type: Ball (for applications requiring high forces and torques) or roller (simple, cost-effective solution), Wide range of sensors Supplied as standard: Protective metal strip, Anti-corrosion version

MAXR_•3

MAXR_{•2}

MAXP

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Tablets

Application name: "Automation Library by Schneider Electric"



Product ranges displayed by function

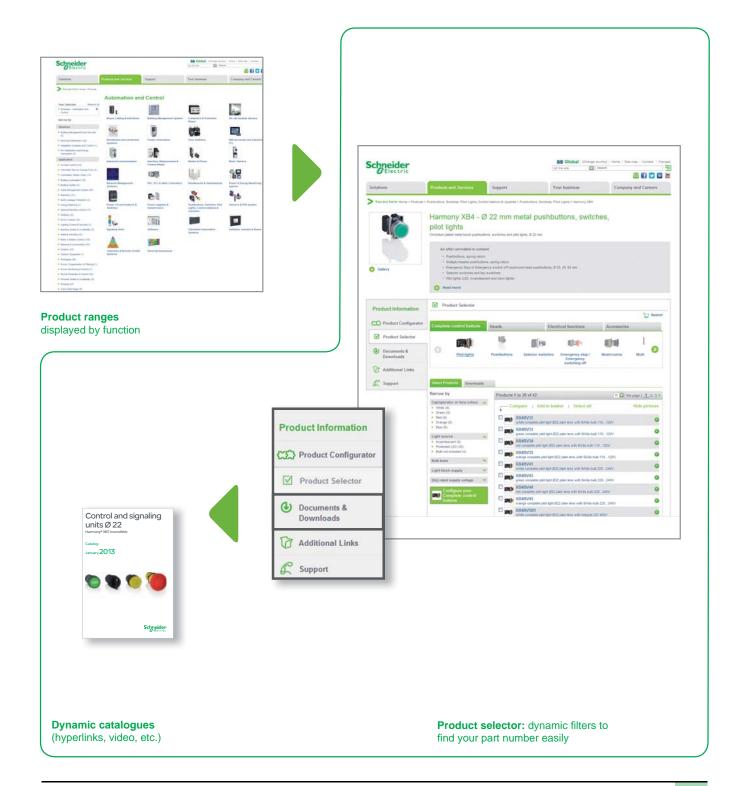








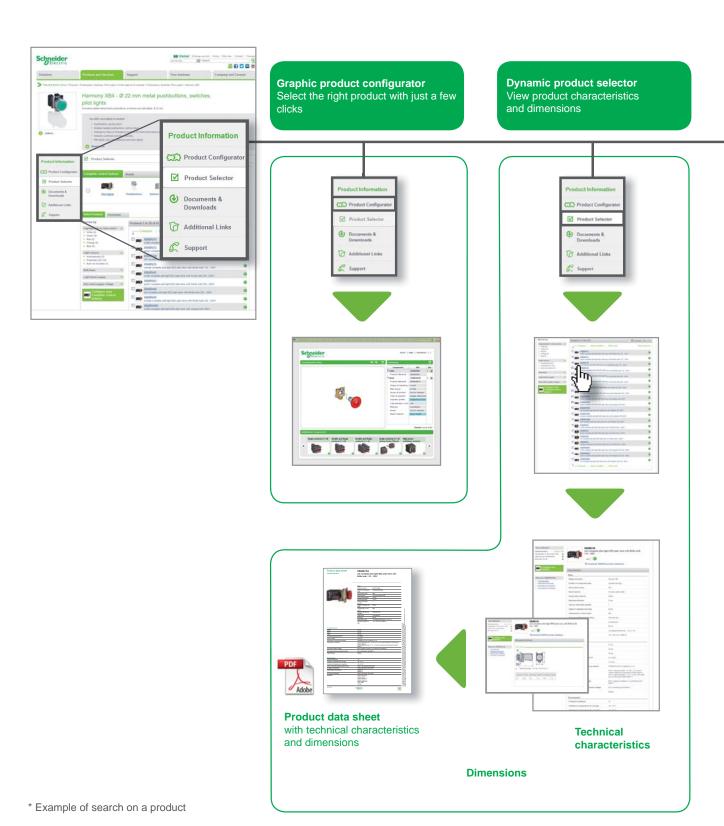
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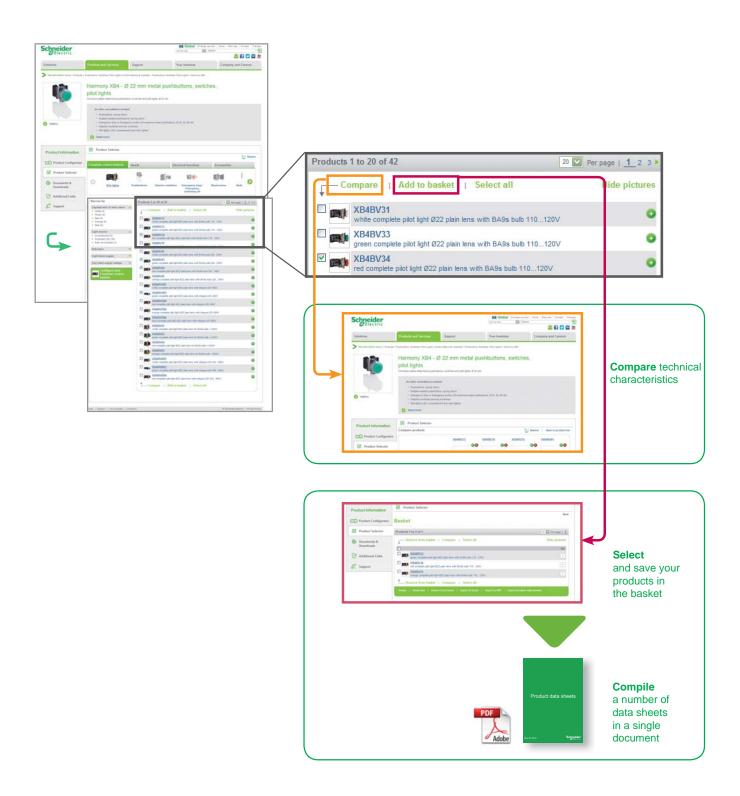
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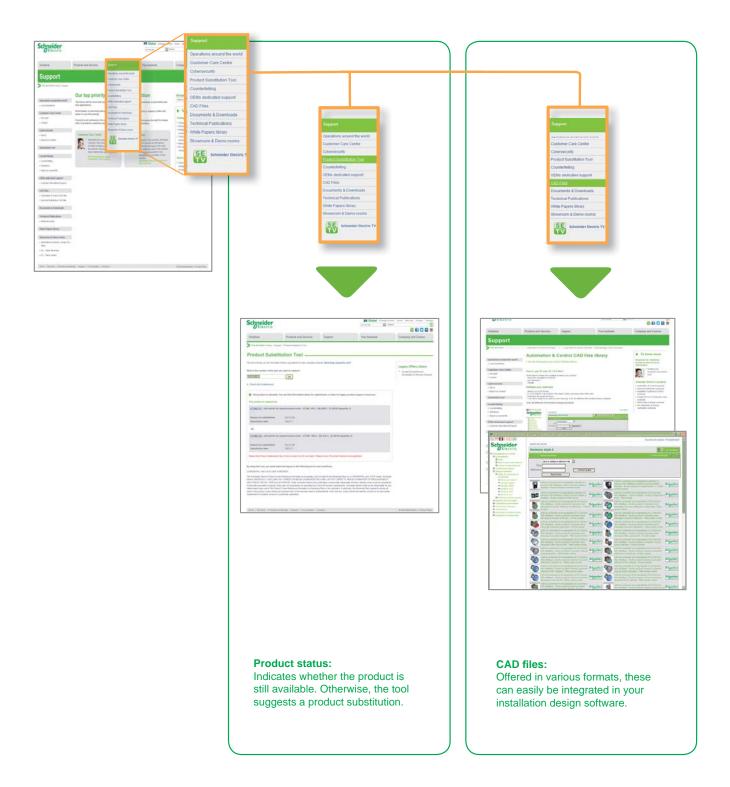
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Please note that references to products and services are just examples.

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